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Dominique Löbach

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On Regularity for plasticity with hardening

Dominique Löbach

Abstract

In this paper we show the regularity of the strain tensor and local differentiability of the stress tensor and hardening parameters in plasticity with hardening using a viscoplastic type penalisation in the case of von Mises yield criterion. The regularity of the strain tensor was first shown by Johnson [Joh78] by constructing a bijection between the strain- and stress tensor. The local differentiability was shown by Seregin [Ser94] with a dual method. In this paper we can bound the strain tensor of the penalized problem on the unit sphere in $L^2(L^2)$ and obtain uniform results in the passage to the limit. This is shown in a more direct way.

Keywords : plasticity with hardening, kinematic hardening, isotropic hardening
regularity of solutions

Subject classification(2000) : primary 74C05 secondary: 35B60, 35K85

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1 The hardening problem

Let $\Omega \subset \mathbb{R}^n$ be an open bounded and connected subset of \mathbb{R}^n with Lipschitz boundary $\partial\Omega$ and $\partial\Omega = \Gamma_N \dot{\cup} \Gamma_D$.

We consider the functions

$$\begin{aligned}\sigma &: \Omega \times [0, T] \rightarrow \mathbb{R}_{\text{sym}}^{n \times n} \\ \xi &: \Omega \times [0, T] \rightarrow \mathbb{R}^m \\ u &: \Omega \times [0, T] \rightarrow \mathbb{R}^n.\end{aligned}$$

Where σ represents the stress tensor, ξ the internal hardening parameters and u the displacement field. The variable t has the character of a loading parameter.

Let $A \in L^\infty(\Omega; \text{hom}(\mathbb{R}_{\text{sym}}^{n \times n}, \mathbb{R}_{\text{sym}}^{n \times n}))$ be a uniformly elliptic, symmetric fourth order tensor field with ellipticity constant $\alpha_A > 0$. That is:

$$(A(x)m) : m \geq \alpha_A |m|^2 \quad \forall m \in \mathbb{R}_{\text{sym}}^{n \times n}.$$

This tensor describes the elastic material properties and is an inverse Hookean law (for example the inverse Lamé-Navier Operator).

Further let the hardening modulus $H \in L^\infty(\Omega; \mathbb{R}^{m \times m})$ be a symmetric, uniform elliptic second order tensor field with ellipticity constant $\alpha_H > 0$.

We define the linearized strain tensor $\varepsilon(u) = \frac{1}{2}(\nabla u + \nabla u^\top)$.

Let $\mathcal{F} : \mathbb{R}_{\text{sym}}^{n \times n} \times \mathbb{R}^m \rightarrow \mathbb{R}$ be a continuous convex function. We call \mathcal{F} a yield function. The yield function \mathcal{F} models the behaviour of the material, that means decides if the material is in an pure elastic respective plastic state.

We assume that $\bar{\Omega}$ is subjected to the following body- and surface force densities

$$\begin{aligned}f &\in L^\infty(0, T; L^n(\Omega, \mathbb{R}^n)) \\ p &\in L^\infty(0, T; L^\infty(\partial\Omega, \mathbb{R}^n)).\end{aligned}\tag{1.1}$$

We consider the following sets of admissible stresses and hardening parameters :

$$\mathcal{K} = \{(\tau, \eta) \in L^2(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n})) \times L^2(0, T; L^2(\Omega, \mathbb{R}^m)) \mid \mathcal{F}(\tau, \eta) \leq 0 \text{ a.e. in } \Omega \times [0, T]\}$$

$$\mathcal{M} = \{(\tau, \eta) \in L^2(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n})) \times L^2(0, T; L^2(\Omega, \mathbb{R}^m)) \mid \tau \cdot \vec{n} = p \text{ on } \Gamma_N, \text{div } \tau \in L^\infty(0, T; L^n(\Omega, \mathbb{R}^n))\}$$

Let $BD(\Omega)$ denote the space of functions with bounded deformation, that is

$$BD(\Omega) = \{u \in L^1(\Omega, \mathbb{R}^n) \mid \varepsilon(u) \in (C_o(\Omega, \mathbb{R}^n))^*\}.$$

This means the strain tensor $\varepsilon(u)$ is only a bounded measure. The space $BD(\Omega)$ can be continuously embedded into $L^{\frac{n}{n-1}}(\Omega, \mathbb{R}^n)$. For further information about $BD(\Omega)$ see Temam [Tem85].

We write $v = \frac{\partial}{\partial t}u(x, t)$ for the "displacement velocity".

Definition 1.1 *The variational inequality of plasticity with hardening is to find $((\sigma, \xi), v) \in (\mathcal{M} \cap \mathcal{K}) \times L^1(0, T; BD(\Omega))$ such that $\dot{\sigma}, \dot{\xi} \in L^2(L^2)$ and for all $(\tau, \eta) \in \mathcal{K} \cap \mathcal{M}$ holds*

$$(A\dot{\sigma}, \tau - \sigma) + (H\dot{\xi}, \eta - \xi) + \langle v, \text{div}(\tau - \sigma) \rangle \geq 0 \quad (1.2)$$

$$\langle \sigma, \nabla w \rangle = \langle f, w \rangle + \int_{\Gamma_N} p w d\Gamma \quad \forall w \in H_{\Gamma_D}^1(\Omega, \mathbb{R}^n) \text{ a.e. with respect to } t$$

$$(\sigma, \xi)(0) = 0 \text{ in } \Omega \times \mathbb{R}^m \times \{t = 0\} \quad (1.3)$$

$$v = 0 \text{ on } \Gamma_D \times [0, T].$$

In this paper we investigate the case of (linear) isotropic and kinematic hardening in the case of von Mises yield criterion.

$$\mathcal{F}(\sigma, \xi) = |\sigma_D| - (\kappa + \xi) \quad \text{isotropic hardening, } \xi \in \mathbb{R}$$

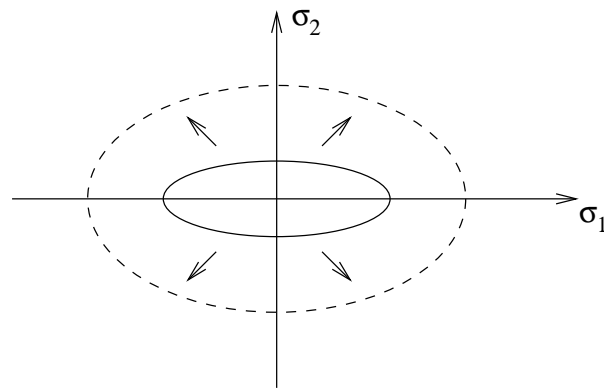
$$\mathcal{F}(\sigma, \xi) = |\sigma_D - \xi_D| - \kappa \quad \text{kinematic hardening, } \xi \in \mathbb{R}_{\text{sym}}^{n \times n}$$

with $\kappa > 0$ the yield limit and $\sigma_D = \sigma - \frac{1}{n} \text{tr}(\sigma) Id$ the deviator of σ .

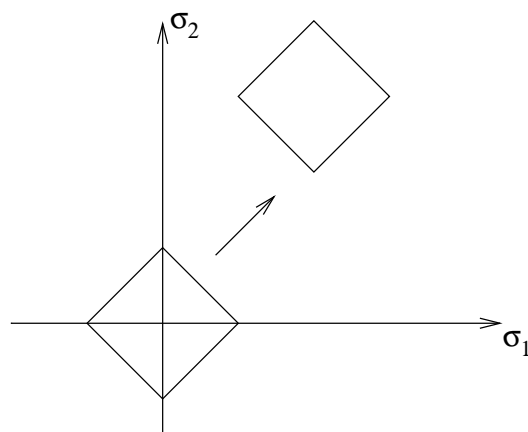
The isotropic hardening describes an uniform expansion of the yield surface, and the yield function takes the form: $\mathcal{F}(\sigma, \xi) = F(\sigma) - \kappa(\xi)$, where F is a continuous, convex and κ a

continuous, concave function.

By kinematic hardening the yield surface undergoes a translation but no change of size or it's shape. The yield function can be written as $\mathcal{F}(\sigma, \xi) = F(\sigma - \xi) - \kappa$ with F continuous and convex.



(a) Isotropic



(b) Kinematic

Figure 1: Isotropic and Kinematic hardening

2 The penalized hardening problem

We will use a viscoplastic type approximation to the hardening problem (1.2). Let us assume, that our yield function $\mathcal{F}(\sigma, \xi)$ is (weak) differentiable. Let $\mu > 0$, we define our viscoplastic potential $G_\mu(\sigma, \xi)$ as

$$G_\mu(\sigma, \xi) := \frac{1}{2\mu} (\mathcal{F}(\sigma, \xi))_+^2 \quad (2.1)$$

$$\text{where } (a)_+ = \begin{cases} a & \text{if } a \geq 0 \\ 0 & \text{if } a < 0. \end{cases}$$

The term $G_\mu(\sigma, \xi)$ is almost everywhere (weak) differentiable and convex. Thus the derivative $G'_\mu(\sigma, \xi)$ is a monotone operator.

We further impose a linear growth condition on the viscoplastic potential derived from the yield function \mathcal{F} . Let \mathcal{F} , such that

$$|\nabla_{(\sigma, \xi)} (\mathcal{F}(\sigma, \xi))_+^2| \leq c_1 |\sigma| + c_2 |\xi| + \text{Const}. \quad (2.2)$$

We now formulate the penalized problem of hardening.

Definition 2.1 Find $((\sigma_\mu, \xi_\mu), v_\mu) \in \mathcal{M} \times L^1(0, T; BD(\Omega))$ such that $(\dot{\sigma}_\mu, \dot{\xi}_\mu) \in L^2(L^2)$ and for all $(\tau, \eta) \in \mathcal{M}$ holds:

$$(A\dot{\sigma}_\mu, \tau - \sigma_\mu) + (H\dot{\xi}_\mu, \eta - \xi_\mu) + (G'_\mu((\sigma_\mu, \xi_\mu)), (\tau - \sigma_\mu, \eta - \xi_\mu)) + \langle v_\mu, \text{div}(\tau - \sigma_\mu) \rangle = 0 \quad (2.3)$$

$$\langle \sigma_\mu, \nabla w \rangle = \langle f, w \rangle + \int_{\Gamma_N} p w d\Gamma \quad \forall w \in H_{\Gamma_D}^1(\Omega, \mathbb{R}^n) \text{ a.e. with respect to } t$$

$$(\sigma_\mu, \xi_\mu)(0) = 0 \text{ in } \Omega \times \mathbb{R}^m \times \{t = 0\} \quad (2.4)$$

$$v_\mu = 0 \text{ on } \Gamma_D \times [0, T]$$

The existence of solutions (σ_μ, ξ_μ) will be shown in section 4.

For $\mu \rightarrow 0$ the sequence $((\sigma_\mu, \xi_\mu), v_\mu)$ converges to the solution of the original hardening problem (1.2). (For the proof see section 6.)

In this paper we consider the von Mises yield criterion and we have:

$$G_\mu(\sigma_\mu, \xi_\mu) = \frac{1}{2\mu} (|\sigma_{\mu D}| - (\kappa + \xi_\mu))_+^2 \quad \text{isotropic hardening}$$

$$G_\mu(\sigma_\mu, \xi_\mu) = \frac{1}{2\mu} (|\sigma_{\mu D} - \xi_{\mu D}| - \kappa)_+^2 \quad \text{kinematic hardening}$$

Our viscoplastic potential (2.1) extends the idea of an associated flow rule. In the context of the Prandtl-Reuss flow rule of perfect plasticity

$$\varepsilon(\dot{u}) = A\dot{\sigma} + \dot{\Pi} \quad (2.5)$$

where Π denotes the plastic strain and $\dot{\Pi} = 0$ if $F(\sigma) \leq 0$ with $F : \mathbb{R}_{\text{sym}}^{n \times n} \rightarrow \mathbb{R}$ a continuous convex yield function.

Attention: The presentation of perfect plasticity in the form (2.5) is common among engineers but only formal in the strict mathematical sense. In perfect plasticity the (elastic) strain tensor $\varepsilon(\dot{u})$ is in the worst case only a bounded measure, thus $\dot{u} \in BD(\Omega)$.

Using formal Green's theorem for ε and by the principle of maximum plastic dissipation (2.7), we derive the variational inequality

$$(A\dot{\sigma}, \tau - \sigma) + \langle \dot{u}, \text{div}(\tau - \sigma) \rangle \geq 0. \quad (2.6)$$

This inequality lacks the boundary and initial conditions, but is the basis for the mathematical formulation of perfect plasticity. (For more details about perfect plasticity see Suquet [Suq81].)

The engineers introduce a plastic potential Φ such that

$$\dot{\Pi} = \dot{\lambda} \frac{\partial}{\partial \sigma} \Phi(\sigma).$$

$\dot{\lambda}$ is a nonnegative (infinitesimal) scalar.

The plastic strain $\dot{\Pi}$ satisfies the the principle of **maximum plastic dissipation** (or maximum plastic work [DL76, HR99])

$$\dot{\Pi} : (\tau - \sigma) \leq 0 \quad \forall \tau : \mathcal{F}(\tau) \leq 0. \quad (2.7)$$

In the context of plasticity with hardening we have ([KL84])

$$\dot{\Pi} = \dot{\lambda} \frac{\partial}{\partial \sigma} \Phi(\sigma, \xi). \quad (2.8)$$

The flow rule (2.8) is called **associated** if Φ is given by the yield function \mathcal{F}

$$\dot{\Pi} = \dot{\lambda} \frac{\partial}{\partial \sigma} \mathcal{F}(\sigma, \xi).$$

In the case of von Mises yield criterion (which we only consider in this paper) a potential of the form

$$\Psi = \frac{1}{2\mu}(\mathcal{F})_+^2$$

is called associated to the **Hohenemser-Prager** model (see Lubliner [Lub90]). In the framework of Han and Reddy [HR99], we consider generalized stresses $\Sigma := (\sigma, \xi)$ and plastic strains $\Pi = (\pi_\sigma, \pi_\xi)$, the associated flow rule

$$\dot{\Pi} = \dot{\lambda} \nabla \mathcal{F}(\Sigma)$$

reads componentwise

$$\begin{aligned} \dot{\pi}_\sigma &= \dot{\lambda} \frac{\partial}{\partial \sigma} \mathcal{F}(\sigma, \xi) \\ \dot{\pi}_\xi &= \dot{\lambda} \frac{\partial}{\partial \xi} \mathcal{F}(\sigma, \xi). \end{aligned} \tag{2.9}$$

In this context the derivative G'_μ of our viscoplastic potential (2.1) satisfies the extended principle of maximum plastic dissipation

$$\dot{\Pi} : (T - \Sigma) \leq 0 \quad \forall T : \mathcal{F}(T) \leq 0.$$

The monotonicity of G'_μ gives for $(\tau, \eta) \in \mathcal{M} \cap \mathcal{K}$

$$(G'_\mu(\sigma, \xi), (\tau - \sigma, \eta - \xi)) \leq 0.$$

The choice (2.1) is an extension of the potential associated to the Hohenemser-Prager model.

3 A priori estimates for the penalized problem

If we make the assumption of a safe load condition (see Johnson [Joh76, Joh78]) one can obtain the existence and estimates for the solutions of the penalized problem independent of μ .

safe load condition:

There exists a $(\tau, \eta) \in W^{1,\infty}(0, T; L^\infty(\Omega, \mathbb{R}^{n \times n}_{\text{sym}})) \times W^{1,\infty}(0, T; L^\infty(\Omega, \mathbb{R}^m))$ and $\delta > 0$ such that

$$\left. \begin{aligned} -\operatorname{div} \tau &= f \text{ in } \Omega \times [0, T] \\ \tau \cdot \vec{n} &= p \text{ on } \Gamma_N \times [0, T] \\ (\tau, \eta)(0) &= 0 \text{ in } \Omega \times \mathbb{R}^m \times \{t = 0\} \\ F(\tau, \eta) &\leq -\delta < 0 \end{aligned} \right\} \quad (3.1)$$

We can now give the following estimates for the sequence of solutions (σ_μ, ξ_μ) of the penalized hardening model. The solvability is shown in section 4.

Theorem 3.1 *Under the assumptions of section 1 and the safe load condition (3.1), the solutions (σ_μ, ξ_μ) of the penalized hardening model satisfy the following estimates independent of μ*

$$\begin{aligned} \|\sigma_\mu\|_{L^\infty(L^2)} &\leq \text{Const} \\ \|\xi_\mu\|_{L^\infty(L^2)} &\leq \text{Const}. \end{aligned} \quad (3.2)$$

proof We choose in equation (2.3) $(\sigma_\mu - \tau, \xi_\mu - \eta)$ where (τ, η) satisfies the safe load condition (3.1)

$$(A\dot{\sigma}_\mu, \sigma_\mu - \tau) + (H\dot{\xi}_\mu, \xi_\mu - \eta) + (G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta)) = 0.$$

Sorting terms

$$(A\dot{\sigma}_\mu, \sigma_\mu) + (H\dot{\xi}_\mu, \xi_\mu) + (G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta)) = (A\dot{\sigma}_\mu, \tau) + (H\dot{\xi}_\mu, \eta). \quad (3.3)$$

Write $(A\dot{\sigma}_\mu, \sigma_\mu), (H\dot{\xi}_\mu, \xi_\mu)$ as time derivative

$$\begin{aligned} (A\dot{\sigma}_\mu, \sigma_\mu) &= \frac{1}{2} \frac{d}{dt} (A\sigma_\mu, \sigma_\mu) \\ (H\dot{\xi}_\mu, \xi_\mu) &= \frac{1}{2} \frac{d}{dt} (H\xi_\mu, \xi_\mu) \end{aligned}$$

and integrate (3.3) from 0 to t

$$\frac{1}{2}(A\sigma_\mu, \sigma_\mu) + \frac{1}{2}(H\xi_\mu, \xi_\mu) + \int_0^t (G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta)) ds \leq \int_0^t (A\dot{\sigma}_\mu, \tau) + (H\dot{\xi}_\mu, \eta) ds. \quad (3.4)$$

The tested penalty term is definite, using the inequality for convex differentiable functions we obtain

$$\int_0^t (G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta)) ds \geq \int_0^t \underbrace{G_\mu((\sigma_\mu, \xi_\mu))}_{\geq 0} - \underbrace{G_\mu((\tau, \eta))}_{=0} ds. \quad (3.5)$$

We use partial integration on the terms of the right hand side of (3.4). (note that $(\sigma_\mu, \xi_\mu)(0) = 0$ and A, H are symmetric)

$$\int_0^t (A\dot{\sigma}_\mu, \tau) + (H\dot{\xi}_\mu, \eta) ds = (\sigma_\mu, A\tau) + (\xi_\mu, H\eta) - \int_0^t (\sigma_\mu, A\dot{\tau}) ds - \int_0^t (\xi_\mu, H\dot{\eta}) ds \quad (3.6)$$

Using Young's inequality gives

$$\begin{aligned} & (\sigma_\mu, A\tau) - \int_0^t (\sigma_\mu, A\dot{\tau}) ds + (\xi_\mu, H\eta) - \int_0^t (\xi_\mu, H\dot{\eta}) ds \\ & \leq \gamma \|\sigma_\mu\|^2 + \frac{1}{4\gamma} \|A\tau\|^2 + \int_0^t \|\sigma_\mu\|^2 ds + \int_0^t \|A\dot{\tau}\|^2 ds \\ & \quad + \rho \|\xi_\mu\|^2 + \frac{1}{4\rho} \|H\eta\|^2 + \int_0^t \|\xi_\mu\|^2 ds + \int_0^t \|H\dot{\eta}\|^2 ds. \end{aligned} \quad (3.7)$$

We choose γ, ρ such that we can absorb terms, using the ellipticity of A and H , equations (3.4) and (3.7) yield

$$\left(\frac{\alpha_A}{2} - \gamma\right) \|\sigma_\mu\|^2 + \left(\frac{\alpha_H}{2} - \rho\right) \|\xi_\mu\|^2 \leq Const + \int_0^t \|\sigma_\mu\|^2 ds + \int_0^t \|\xi_\mu\|^2 ds. \quad (3.8)$$

The Gronwall lemma implies that $\|\sigma_\mu\|$ and $\|\xi_\mu\|$ are bounded.

This proves the statement of the theorem. \square

These results lead to

Theorem 3.2 *Under the assumptions of theorem 3.1, we have*

$$\begin{aligned} \|G_\mu(\sigma_\mu, \xi_\mu)\|_{L^1(L^1)} & \leq Const \\ \|G'_\mu(\sigma_\mu, \xi_\mu)\|_{L^1(L^1)} & \leq Const. \end{aligned} \quad (3.9)$$

proof The results from theorem 3.1 and lemma 2 from [Suq81] yield the estimates. \square

4 Existence of solutions of the penalized hardening problem

We will now show the existence of solutions $((\sigma_\mu, \xi), v_\mu)$ and time derivatives of the stress tensor and hardening parameters in the penalized hardening model.

Theorem 4.1 *Under the assumptions of section 1 and the safe load condition (3.1), there exists a solution $((\sigma_\mu, \xi_\mu), v_\mu)$ of the penalized hardening problem (2.3). The time derivatives of the stress tensor $\dot{\sigma}_\mu$ and the hardening parameter $\dot{\xi}_\mu$ exist and we have the estimates independent of the penalty parameter μ*

$$\begin{aligned}\|\dot{\sigma}_\mu\|_{L^2(L^2)} &\leq Const \\ \|\dot{\xi}_\mu\|_{L^2(L^2)} &\leq Const.\end{aligned}\tag{4.1}$$

proof

1) We discretize the weak formulation (2.3) of penalized plasticity with hardening in time with finite backward differences.

Let $N \in \mathbb{N}^+$, $k = \frac{T}{N}$ the step size in time direction and $\eta^m = \eta(m \cdot k)$. Write

$$D_t^{-k} \eta^m = \frac{\eta^m - \eta^{m-1}}{k}$$

for finite backward differences in time. The time discretized formulation is now

$$\begin{aligned}(AD_t^{-k} \sigma_\mu^m, \sigma_\mu^m - \chi^m) + (HD_t^{-k} \xi_\mu^m, \xi_\mu^m - \omega^m) + (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), (\sigma_\mu^m - \chi^m, \xi_\mu^m - \omega^m)) \\ + \langle v_\mu^m, \text{div}(\sigma_\mu^m - \chi^m) \rangle = 0.\end{aligned}\tag{4.2}$$

The balance of forces (1.3) is altered in the following way:

$$\begin{aligned}\text{div } \sigma_\mu^m &= \frac{1}{k} \int_{m \cdot k}^{(m+1) \cdot k} f \, ds \\ \sigma_\mu^m \cdot \vec{n} &= \frac{1}{k} \int_{m \cdot k}^{(m+1) \cdot k} p \, ds \text{ on } \Gamma_N.\end{aligned}\tag{4.3}$$

We approximate the pair (τ, η) in the safe load condition(3.1) by

$$\begin{aligned}\tau^m &= \frac{1}{k} \int_{m \cdot k}^{(m+1) \cdot k} \tau \, ds \\ \eta^m &= \frac{1}{k} \int_{m \cdot k}^{(m+1) \cdot k} \eta \, ds,\end{aligned}\tag{4.4}$$

and as in (4.3) we let (τ^m, η^m) satisfy the altered balance of forces. By the convexity of \mathcal{K} the altered a discrete analog of the safe load condition still holds

$$\mathcal{F}(\tau^m, \eta^m) < 0 \text{ a.e. in } \Omega. \quad (4.5)$$

The existence of a solution $(\sigma_\mu^m, \xi_\mu^m)$ on every time step m , of the discretized formulation (4.2) for μ, k fixed can be shown by direct methods in the calculus of variations.

We consider the energy functional J_μ^m :

$$J_\mu^m(\sigma_\mu^m, \xi_\mu^m) := \frac{1}{2k} (A\sigma_\mu^m, \sigma_\mu^m) - \frac{1}{k} (A\sigma_\mu^m, \sigma_\mu^{m-1}) + \frac{1}{2k} (H\xi_\mu^m, \xi_\mu^m) - \frac{1}{k} (H\xi_\mu^m, \xi_\mu^{m-1}) + G_\mu(\sigma_\mu^m, \xi_\mu^m). \quad (4.6)$$

The Euler-Lagrange equation of (4.6) is just the time discretized equation (4.2) without the term $\langle v_\mu^m, \operatorname{div}(\sigma_\mu^m - \chi^m) \rangle$.

The existence of the displacement velocity $v_\mu^m \in H_{\Gamma_D}^1(\Omega, \mathbb{R}^n)$ can be shown in a similar way to Anzellotti & Giaquinata [AG80, AG82] since J_μ^m is a perturbed Hencky like energy functional.

2) We now introduce the operator I_p^k of piece wise constant interpolation in time as

$$I_p^k \sigma(t) := \frac{1}{k} \int_{m \cdot k}^{(m+1) \cdot k} \sigma^m(s) ds, \quad m \cdot k \leq t \leq (m+1) \cdot k, \quad m = 1, \dots, N. \quad (4.7)$$

With similar methods as exposed in the non-discrete case in section 3 we obtain $L^\infty(L^2)$ estimates for $(I_p^k \sigma_\mu, I_p^k \xi_\mu)$

$$\begin{aligned} \|I_p^k \sigma_\mu\|_{L^\infty(L^2)} &\leq \text{Const} \\ \|I_p^k \xi_\mu^m\|_{L^\infty(L^2)} &\leq \text{Const}. \end{aligned} \quad (4.8)$$

As in section 3 choose $(\sigma_\mu^m - \tau^m, \xi_\mu^m - \eta^m)$ in equation (4.2) and then argue as in [Joh76].

3) Let $\bar{\sigma} = \sigma_\mu - \tau$ and $\bar{\xi} = \xi_\mu - \eta$, where (τ, η) satisfies the safe load condition. Test the discretized equation (4.2) with $D_t^{-k}(\bar{\sigma}^m, \bar{\xi}^m)$.

$$(AD_t^{-k} \sigma_\mu^m, D_t^{-k} \bar{\sigma}^m) + (HD_t^{-k} \xi_\mu^m, D_t^{-k} \bar{\xi}^m) + (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), D_t^{-k}(\bar{\sigma}^m, \bar{\xi}^m)) = 0$$

sorting terms

$$\begin{aligned} (AD_t^{-k} \sigma_\mu^m, D_t^{-k} \sigma_\mu^m) + (HD_t^{-k} \xi_\mu^m, D_t^{-k} \xi_\mu^m) + (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), D_t^{-k}(\bar{\sigma}^m, \bar{\xi}^m)) \\ = (AD_t^{-k} \sigma_\mu^m, D_t^{-k} \tau^m) + (HD_t^{-k} \xi_\mu^m, D_t^{-k} \eta^m) \end{aligned} \quad (4.9)$$

using on the righthand side the symmetry of A , H and Young's inequality with $0 < \rho < \alpha_A$, $0 < \gamma < \alpha_H$, set $c_1 := \alpha_A - \rho$, $c_2 := \alpha_H - \gamma$

$$c_1 \|D_t^{-k} \sigma_\mu^m\|^2 + c_2 \|D_t^{-k} \xi_\mu^m\|^2 + (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), D_t^{-k}(\bar{\sigma}^m, \bar{\xi}^m)) \leq \frac{1}{4\rho} \|AD_t^{-k} \tau^m\|^2 + \frac{1}{4\gamma} \|HD_t^{-k} \eta^m\|^2. \quad (4.10)$$

Because (τ, η) satisfies the safe load condition we have

$$c_1 \|D_t^{-k} \sigma_\mu^m\|^2 + c_2 \|D_t^{-k} \xi_\mu^m\|^2 + (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), D_t^{-k}(\sigma_\mu^m, \xi_\mu^m)) \leq Const(\rho) + (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), D_t^{-k}(\tau^m, \eta^m)). \quad (4.11)$$

We can estimate the tested penalty term as follows

$$\begin{aligned} (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), D_t^{-k}(\tau^m, \eta^m)) &= \int_\Omega G'_\mu((\sigma_\mu^m, \xi_\mu^m)) : (D_t^{-k}(\tau^m, \eta^m)) dx \\ &\leq \int_\Omega |G'_\mu((\sigma_\mu^m, \xi_\mu^m))| \cdot |D_t^{-k}(\tau^m, \eta^m)| dx \\ &\leq \int_\Omega |G'_\mu((\sigma_\mu^m, \xi_\mu^m))| \cdot |(\dot{\tau}^m, \dot{\eta}^m)| dx \\ &\leq C \int_\Omega |G'_\mu((\sigma_\mu^m, \xi_\mu^m))| dx. \end{aligned} \quad (4.12)$$

Hence

$$c_1 \|D_t^{-k} \sigma_\mu^m\|^2 + c_2 \|D_t^{-k} \xi_\mu^m\|^2 + (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), D_t^{-k}(\sigma_\mu^m, \xi_\mu^m)) \leq C \int_0^t |G'_\mu((\sigma_\mu^m, \xi_\mu^m))| dx + Const. \quad (4.13)$$

Multiply this equation by k and sum over $m = 1, \dots, N$

$$\begin{aligned} c_1 k \sum_{m=1}^N \|D_t^{-k} \sigma_\mu^m\|^2 + c_2 k \sum_{m=1}^N \|D_t^{-k} \xi_\mu^m\|^2 + \underbrace{\sum_{m=1}^N (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), (\sigma_\mu^m - \sigma_\mu^{m-1}, \xi_\mu^m - \xi_\mu^{m-1}))}_{(*)} \\ \leq Const \cdot T + Ck \sum_{m=1}^N \int_\Omega |G'_\mu(\sigma_\mu^m, \xi_\mu^m)| dx. \end{aligned} \quad (4.14)$$

The term $(*)$ is non negative, the inequality for convex differentiable functions yields

$$\int_\Omega G_\mu((\sigma_\mu^m, \xi_\mu^m)) - G_\mu((\sigma_\mu^{m-1}, \xi_\mu^{m-1})) dx \leq (G'_\mu((\sigma_\mu^m, \xi_\mu^m)), (\sigma_\mu^m - \sigma_\mu^{m-1}, \xi_\mu^m - \xi_\mu^{m-1})).$$

Summing from $m = 1, \dots, N$ gives a telescope sum

$$\begin{aligned}
(*) &= \sum_{m=1}^N (G'_\mu(\sigma_\mu^m, \xi_\mu^m), (\sigma_\mu^m - \sigma_\mu^{m-1}, \xi_\mu^m - \xi_\mu^{m-1})) \geq \sum_{m=1}^N \int_{\Omega} G_\mu((\sigma_\mu^m, \xi_\mu^m)) - G_\mu((\sigma_\mu^{m-1}, \xi_\mu^{m-1})) dx \\
&= \int_{\Omega} G_\mu((\sigma_\mu^N, \xi_\mu^N)) - G_\mu((\sigma_\mu^0, \xi_\mu^0)) dx \geq 0.
\end{aligned} \tag{4.15}$$

By a discrete analogue of theorem 3.2, we have $G'_\mu((\sigma_\mu, \xi_\mu))$ bounded in $L^1(0, T; L^1(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}))$, a choice of k sufficiently small enough yields

$$\begin{aligned}
Ck \sum_{m=1}^N \int_{\Omega} |G'_\mu((\sigma_\mu^m, \xi_\mu^m))| dx &\leq C \|G'_\mu(I_p^k(\sigma_\mu, \xi_\mu))\|_{L^1(L^1)} \leq \text{Const}. \\
k \sum_{m=1}^N \|D_t^{-k} \sigma_\mu^m\|^2 + k \sum_{m=1}^N \|D_t^{-k} \xi_\mu^m\|^2 &\leq \text{Const} \cdot T.
\end{aligned}$$

Hence, for k sufficiently small

$$\begin{aligned}
\|I_p^k D_t^{-k} \sigma_\mu\|_{L^2(L^2)} &\leq \text{Const} \\
\|I_p^k D_t^{-k} \xi_\mu\|_{L^2(L^2)} &\leq \text{Const}.
\end{aligned} \tag{4.16}$$

4) The boundedness of $(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m)$ (4.8) and $D_t^{-k}(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m)$ (4.16) yield the existence of $(\tilde{\sigma}_\mu, \tilde{\xi}_\mu)$ and the weak convergene in $L^2(L^2)$

$$\begin{aligned}
(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m) &\rightharpoonup (\tilde{\sigma}_\mu, \tilde{\xi}_\mu) \\
D_t^{-k}(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m) &\rightharpoonup (\dot{\tilde{\sigma}}_\mu, \dot{\tilde{\xi}}_\mu),
\end{aligned} \tag{4.17}$$

as $k \rightarrow 0$.

We will now show for μ fixed the strong convergence of $(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m)$: Test the discretized equation (4.2) with $(I_p^k \sigma_\mu^m - \tilde{\sigma}_\mu, I_p^k \xi_\mu^m - \tilde{\xi}_\mu)$

$$0 = (AD_t^{-k} I_p^k \sigma_\mu^m, I_p^k \sigma_\mu^m - \tilde{\sigma}_\mu) + (HD_t^{-k} I_p^k \xi_\mu^m, I_p^k \xi_\mu^m - \tilde{\xi}_\mu) + (G'_\mu(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m), (I_p^k \sigma_\mu^m - \tilde{\sigma}_\mu, I_p^k \xi_\mu^m - \tilde{\xi}_\mu)). \tag{4.18}$$

Note that, on can interchange the interpolation operation with the nonlinearity in G'_μ , since I_p^k is piece wise constant.

We set $z^m := I_p^k \sigma_\mu^m - \tilde{\sigma}_\mu$, $g^m := I_p^k \xi_\mu^m - \tilde{\xi}_\mu$ and using the monotonicity of the penalty term $G'_\mu(I - p^k \sigma_\mu^m, I_p^k \xi_\mu^m)$ we obtain

$$o(1) = \left(AD_t^{-k} z^m, z^m, z^m \right) + \left(HD_t^{-k} g^m, g^m \right) + \underbrace{\left(G'_\mu((I - p^k \sigma_\mu^m, I_p^k \xi_\mu^m)) - G'_\mu((\tilde{\sigma}_\mu, \tilde{\xi}_\mu)) \right)}_{\geq 0} (z^m, g^m). \quad (4.19)$$

Using Young's inequality

$$\begin{aligned} o(1) &\geq \frac{1}{2k} (Az^m, z^m) - \frac{1}{2k} (Az^{m-1}, z^{m-1}) \\ &\quad + \frac{1}{2k} (Hg^m, g^m) - \frac{1}{2k} (Hg^{m-1}, g^{m-1}). \end{aligned} \quad (4.20)$$

Summing over $m = 0, \dots, l \leq N$ we have

$$o(1) \geq \frac{1}{2k} (Az^l, z^l) + \frac{1}{2k} (Hg^l, g^l). \quad (4.21)$$

Where we have use that we define $(I_p^k \sigma_\mu^m, \xi_\mu^m)(s) = 0$ for $0 \leq s \leq \delta$, in order to satisfy the initial value.

This gives the strong convergene of $(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m) \rightarrow (\tilde{\sigma}_\mu, \tilde{\xi}_\mu)$ and as $k \rightarrow 0$ by fixed viscosity coefficient μ .

5) We have now to show, that $(\tilde{\sigma}_\mu, \tilde{\xi}_\mu)$ are solutions of the penalized hardening problem (2.3). Test the discretized equation (4.2) with $(I_p^k \sigma_\mu^m - \tau, I_p^k \xi_\mu^m - \eta)$, where (τ, η) satisfies the safe load condition.

$$0 = \left(AD_t^{-k} I_p^k \sigma_\mu^m, I_p^k \sigma_\mu^m - \tau \right) + \left(HD_t^{-k} I_p^k \xi_\mu^m, I_p^k \xi_\mu^m - \eta \right) + \left(G'_\mu((I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m)), (I_p^k \sigma_\mu^m - \tau, I_p^k \xi_\mu^m - \eta) \right) \quad (4.22)$$

Due to the strong convergence of $(I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m) \rightarrow (\tilde{\sigma}_\mu, \tilde{\xi}_\mu)$ and the weak convergence $D_t^{-k} (I_p^k \sigma_\mu^m, I_p^k \xi_\mu^m) \rightarrow (\dot{\tilde{\sigma}}_\mu, \dot{\tilde{\xi}}_\mu)$ we get

$$0 = \left(A\dot{\tilde{\sigma}}_\mu, \tilde{\sigma}_\mu - \tau \right) + \left(H\dot{\tilde{\xi}}_\mu, \tilde{\xi}_\mu - \eta \right) + \left(G'_\mu((\tilde{\sigma}_\mu, \tilde{\xi}_\mu)), (\tilde{\sigma}_\mu - \tau, \tilde{\xi}_\mu - \eta) \right). \quad (4.23)$$

□

5 Pointwise a.e. equation for the penalized model

The estimates of the last section allow us to show that for fixed viscosity coefficient μ the strain tensor $\varepsilon(v_\mu)$ is a square integrable function.

Theorem 5.1 *For fixed viscosity coefficient μ we have*

$$\begin{aligned} \|\varepsilon(v_\mu)\|_{L^2(L^2)} &\leq \text{Const}(\mu) \\ \|v_\mu\|_{L^2(H^1)} &\leq \text{Const}(\mu). \end{aligned} \quad (5.1)$$

proof Consider the weak formulation (2.3) of penalized hardening.

$$(A\dot{\sigma}_\mu, \chi - \sigma_\mu) + (H\dot{\xi}_\mu, \omega - \xi_\mu) + (G'_\mu((\sigma_\mu, \xi_\mu)), (\chi - \sigma_\mu, \omega - \xi_\mu)) + \langle v_\mu, \text{div}(\chi - \sigma_\mu) \rangle = 0$$

Choose $(\chi, \omega) \in L^2(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n})) \times L^2(0, T; L^2(\Omega, \mathbb{R}^m))$ with

$$\left. \begin{aligned} -\text{div} \chi &= f \text{ in } \Omega \\ \chi \cdot \vec{n} &= p \text{ on } \Gamma_N \\ \omega &= \xi_\mu. \end{aligned} \right\} \quad (5.2)$$

Inserting (χ, ω) into the weak formulation results

$$(A\dot{\sigma}_\mu, \chi - \sigma_\mu) + (G'_\mu((\sigma_\mu, \xi_\mu)), (\chi - \sigma_\mu, 0)) = 0. \quad (5.3)$$

The space of divergence free tensor fields is the orthogonal complement of the space of strain tensors ([Tem85] see e.g. also [Löb07a]). This implies

$$A\dot{\sigma}_\mu + \frac{\partial}{\partial \sigma_\mu} G_\mu((\sigma_\mu, \xi_\mu)) = \varepsilon(v_\mu) \quad (5.4)$$

pointwise almost everywhere in Ω for t fixed. We have $\varepsilon(v_\mu) \in L^2(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}))$ and

$$(A\dot{\sigma}_\mu, \chi - \sigma_\mu) + (H\dot{\xi}_\mu, \omega - \xi_\mu) + (G'_\mu((\sigma_\mu, \xi_\mu)), (\chi - \sigma_\mu, \omega - \xi_\mu)) - (\varepsilon(v_\mu), \chi - \sigma_\mu) = 0. \quad (5.5)$$

The linear growth condition (2.2) and $\|\sigma_\mu\|_{L^\infty(L^2)}, \|\xi_\mu\|_{L^\infty(L^2)} \leq \text{Const}$ gives the estimate

$$\|G'_\mu((\sigma_\mu, \xi_\mu))\|_{L^2(L^2)} \leq \frac{1}{\mu} \text{Const}. \quad (5.6)$$

Together with Korn's inequality

$$\begin{aligned} \|\varepsilon(v_\mu)\|_{L^2(L^2)} &\leq \frac{1}{\mu} \text{Const} \\ \|v_\mu\|_{L^2(H^1)} &\leq \frac{1}{\mu} \text{Const}. \end{aligned}$$

□

This leads to the pointwise almost everywhere equation

$$\begin{pmatrix} A\dot{\sigma}_\mu \\ H\dot{\xi}_\mu \end{pmatrix} + \begin{pmatrix} \frac{\partial}{\partial \sigma_\mu} G_\mu(\sigma_\mu, \xi_\mu) \\ \frac{\partial}{\partial \xi_\mu} G_\mu(\sigma_\mu, \xi_\mu) \end{pmatrix} = \begin{pmatrix} \varepsilon(v_\mu) \\ 0 \end{pmatrix}. \quad (5.7)$$

We obtain a formulation containing the strain tensor $\varepsilon(v_\mu)$.

Find $((\sigma_\mu, \xi_\mu), v_\mu)$ such that for all $(\tau, \eta) \in \mathcal{M}$ holds

$$(A\dot{\sigma}_\mu, \tau - \sigma_\mu) + (H\dot{\xi}_\mu, \eta - \xi_\mu) + (G'_\mu((\sigma_\mu, \xi_\mu)), (\tau - \sigma_\mu, \eta - \xi_\mu)) - (\varepsilon(v_\mu), \tau - \sigma_\mu) = 0 \quad (5.8)$$

6 Convergence of the penalized problem to the hardening model

We will now prove the convergence of the stress tensor and hardening parameter (σ_μ, ξ_μ) to the solution of the initial hardening problem (1.2).

Theorem 6.1 *There exists a subsequence of the sequence (σ_μ, ξ_μ) of solutions of the penalized hardening problem (2.3), converging weakly in $L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n})) \times L^2(0, T; L^2(\Omega; \mathbb{R}^m))$ to the solution of the initial hardening problem (1.2).*

proof From theorems 3.1 and 4.1 we know that the sequence of the stress tensor, hardening parameters and their time derivatives is uniformly bounded in $L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n})) \times L^2(0, T; L^2(\Omega; \mathbb{R}^m))$.

Extracting a suitable subsequence $(\sigma_{\mu_l}, \xi_{\mu_l})$, there exists $(\tilde{\sigma}, \tilde{\xi}) \in L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n})) \times L^2(0, T; L^2(\Omega; \mathbb{R}^m))$ such that for $\mu_l \rightarrow 0$

$$\begin{aligned} (\sigma_{\mu_l}, \xi_{\mu_l}) &\rightharpoonup (\tilde{\sigma}, \tilde{\xi}) \\ (\dot{\sigma}_{\mu_l}, \dot{\xi}_{\mu_l}) &\rightharpoonup (\dot{\tilde{\sigma}}, \dot{\tilde{\xi}}). \end{aligned} \tag{6.1}$$

Define

$$\mathcal{X} := \mathcal{M} \cap \{(\tau, \eta) \in L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n})) \times L^2(0, T; L^2(\Omega; \mathbb{R}^m)) \mid -\operatorname{div} \tau = f \text{ in } \Omega \times [0, T]\}$$

Test the pointwise almost everywhere penalized hardening law (5.8) with $(\tau - \sigma_{\mu_l}, \eta - \xi_{\mu_l})$ where $(\tau, \eta) \in \mathcal{K} \cap \mathcal{X}$. Then we have a.e. on $[0, T]$

$$(A\dot{\sigma}_{\mu_l}, \tau - \sigma_{\mu_l}) + (H\dot{\xi}_{\mu_l}, \eta - \xi_{\mu_l}) + (G'_\mu((\sigma_{\mu_l}, \xi_{\mu_l})), (\tau - \sigma_{\mu_l}, \eta - \xi_{\mu_l})) = 0. \tag{6.2}$$

The tested penalty term is non positive

$$(G'_\mu((\sigma_{\mu_l}, \xi_{\mu_l})), (\tau - \sigma_{\mu_l}, \eta - \xi_{\mu_l})) \leq \underbrace{G_\mu(\tau, \eta)}_{=0} - \underbrace{G_\mu(\sigma_{\mu_l}, \xi_{\mu_l})}_{\geq 0}.$$

This yields

$$(A\dot{\sigma}_{\mu_l}, \tau - \sigma_{\mu_l}) + (H\dot{\xi}_{\mu_l}, \eta - \xi_{\mu_l}) \geq 0. \tag{6.3}$$

From (6.3) we infer (note $(\sigma_{\mu_l}, \xi_{\mu_l})(0) = 0$)

$$\begin{aligned} 0 &\leq \limsup_{\mu_l \rightarrow 0} \left[-\int_0^t (A\dot{\sigma}_{\mu_l}, \sigma_{\mu_l}) ds + \int_0^t (A\dot{\sigma}_{\mu_l}, \tau) ds - \int_0^t (H\dot{\xi}_{\mu_l}, \xi_{\mu_l}) ds + \int_0^t (H\dot{\xi}_{\mu_l}, \eta) ds \right] \\ &\leq \limsup_{\mu_l \rightarrow 0} \left[-\frac{1}{2}(A\sigma_{\mu_l}, \sigma_{\mu_l})(t) - \frac{1}{2}(H\xi_{\mu_l}, \xi_{\mu_l})(t) + \int_0^t (A\dot{\sigma}_{\mu_l}, \tau) ds + \int_0^t (H\dot{\xi}_{\mu_l}, \eta) ds \right]. \end{aligned} \tag{6.4}$$

We average with respect to t on an interval $(s, s+h)$ and use that

$$-\frac{1}{2h} \int_s^{s+h} (A\sigma_{\mu_l}, \sigma_{\mu_l})(t) dt - \frac{1}{2h} \int_s^{s+h} (H\xi_{\mu_l}, \xi_{\mu_l})(t) dt$$

are upper semicontinuous in the weak topology on $L^2(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}))$, thus

$$(6.4) \leq \limsup_{\mu_l \rightarrow 0} \left[-\frac{1}{2h} \int_s^{s+h} (A\sigma_{\mu_l}, \sigma_{\mu_l})(t) dt - \frac{1}{2h} \int_s^{s+h} (H\xi_{\mu_l}, \xi_{\mu_l})(t) dt \right. \\ \left. + \frac{1}{h} \int_s^{s+h} \int_0^t (A\dot{\sigma}_{\mu_l}, \tau) ds dt + \frac{1}{h} \int_s^{s+h} \int_0^t (H\dot{\xi}_{\mu_l}, \eta) ds dt \right] \quad (6.5)$$

By the the weak convergence (6.1) and $(\sigma_{\mu}, \xi_{\mu})(0) = 0$ we deduce almost everywhere in $[0, T]$

$$0 \leq \left[-\frac{1}{2h} \int_s^{s+h} (A\tilde{\sigma}, \tilde{\sigma}) dt - \frac{1}{2h} \int_s^{s+h} (H\tilde{\xi}, \tilde{\xi}) dt + \frac{1}{h} \int_s^{s+h} \int_0^t (A\dot{\tilde{\sigma}}, \tau) ds dt + \frac{1}{h} \int_s^{s+h} \int_0^t (H\dot{\tilde{\xi}}, \eta) ds dt \right]. \quad (6.6)$$

The weak limit $\tilde{\sigma}$ satisfies $\tilde{\sigma}(0) = 0$, since $\sigma_{\mu}, \dot{\sigma}_{\mu}$ are uniform bounded in $L^\infty(L^2), L^2(L^2)$ with respect to the viscosity coefficient μ .

Now, we let $h \rightarrow 0$, and a theorem about Lebesgue points provides for almost all $t \in [0, T]$

$$0 \leq \int_0^t (A\dot{\tilde{\sigma}}, \tau - \tilde{\sigma}) ds + \int_0^t (H\dot{\tilde{\xi}}, \eta - \tilde{\xi}) ds. \quad (6.7)$$

Since $(\sigma_{\mu_l}, \xi_{\mu_l}) \in \mathcal{X}$ and \mathcal{X} is closed and convex the weak limit satisfies $(\tilde{\sigma}, \tilde{\xi}) \in \mathcal{X}$. We have to show that $(\tilde{\sigma}, \tilde{\xi}) \in \mathcal{K}$. By theorem 3.2 we have

$$\int_0^T (F(\sigma_{\mu_l}, \xi_{\mu_l}))_+^2 ds \leq \mu_l \cdot Const.$$

By letting $\mu_l \rightarrow 0$, we obtain $(\tilde{\sigma}, \tilde{\xi}) \in \mathcal{K}$ and this proves the statement of the theorem. By standard techniques we obtain the convergence of the whole sequence $(\sigma_{\mu}, \xi_{\mu})$. \square

Now we show the convergence of the displacement velocity v_{μ} .

Theorem 6.2 *There exists a subsequence (v_{μ_l}) converging weakly in $L^2(0, T; H_{\text{D}}^1(\Omega, \mathbb{R}^n))$ to v displacement velocity solution of the initial hardening problem (1.2).*

proof We will make use of results from the next section. By theorems 7.1, 7.3 in section 7 we know that the sequence (v_μ) is uniformly bounded in $L^2(0, T; H_{\Gamma_D}^1(\Omega, \mathbb{R}^n))$. Thus there exists a $\hat{v} \in L^2(0, T; H_{\Gamma_D}^1(\Omega, \mathbb{R}^n))$ and a suitable subsequence $((\sigma_{\mu_l}, \xi_{\mu_l}), v_{\mu_l})$ such that for $\mu_l \rightarrow 0$

$$((\sigma_{\mu_l}, \xi_{\mu_l}), v_{\mu_l}) \rightharpoonup ((\sigma, \xi), \hat{v}).$$

We have to show that \hat{v} is a solution of (1.2).

Test equation (5.8) with $(\sigma_\mu - \tau, \xi_\mu - \eta)$ where $(\tau, \eta) \in \mathcal{M}$. We have like in theorem 6.1 by using the balance of forces (2.4)

$$-(v_{\mu_l}, \operatorname{div}(\sigma_{\mu_l} - \tau)) \geq (A\dot{\sigma}_{\mu_l}, \sigma_{\mu_l} - \tau) + (H\dot{\xi}_{\mu_l}, \xi_{\mu_l} - \eta) \text{ a.e. in } [0, T]. \quad (6.8)$$

Arguing as in the preceding theorem we see that \hat{v} is the displacement velocity solution to the initial hardening problem (1.2). \square

Theorem 6.3 *The sequence (σ_μ, ξ_μ) converges strongly in $L^2(L^2)$.*

proof Test (5.8) with $(\sigma - \sigma_\mu, \xi - \xi_\mu)$, where (σ, ξ) is a solution of (1.2)

$$(A\dot{\sigma}_\mu, \sigma - \sigma_\mu) + (H\dot{\xi}_\mu, \xi - \xi_\mu) + (G'_\mu(\sigma_\mu, \xi_\mu), (\sigma - \sigma_\mu, \xi - \xi_\mu)) = 0. \quad (6.9)$$

Due to the monotonicity of G'_μ the tested penalty term is non negative. Hence

$$(A(\dot{\sigma} - \dot{\sigma}_\mu), \sigma - \sigma_\mu) + (H(\dot{\xi} - \dot{\xi}_\mu), \xi - \xi_\mu) \leq (A\dot{\sigma}, \sigma - \sigma_\mu) + (H\dot{\xi}, \xi - \xi_\mu). \quad (6.10)$$

Integration of (6.10) from 0 to t yields

$$\frac{1}{2}(A(\sigma - \sigma_\mu), \sigma - \sigma_\mu) + \frac{1}{2}(H(\xi - \xi_\mu), \xi - \xi_\mu) \leq \int_0^t (A\dot{\sigma}, \sigma - \sigma_\mu) ds + \int_0^t (H\dot{\xi}, \xi - \xi_\mu) ds. \quad (6.11)$$

Passing to the limit $\mu \rightarrow 0$ gives

$$\liminf_{\mu \rightarrow 0} \frac{1}{2} \left[(A(\sigma - \sigma_\mu), \sigma - \sigma_\mu) + (H(\xi - \xi_\mu), \xi - \xi_\mu) \right] \leq \underbrace{\lim_{\mu \rightarrow 0} \left[\int_0^t (A\dot{\sigma}, \sigma - \sigma_\mu) ds + \int_0^t (H\dot{\xi}, \xi - \xi_\mu) ds \right]}_{=0} \quad (6.12)$$

since $(\sigma_\mu, \xi_\mu) \rightharpoonup (\sigma, \xi)$. \square

7 H^1 -Regularity

In this section we show the regularity of the hardening model. Johnson ([Joh78]) was the first to show the H^1 -regularity for the displacement velocities. He used as approximation the projection onto the set of all stress and hardening parameter satisfying the yield criterion.(see e.g. Duvaut Lions [DL76] for projection models.) Seregin [Ser94] even obtained H_{loc}^2 regularity results for the displacements (not velocities!) in kinematic hardening.

We show the uniform boundedness for $\varepsilon(v_\mu)$ and then we regard the stress tensor. The proof in the present paper looks simpler, although it is, of course, similar. The regularity problem for the displacement velocities was also discussed in [Pai02].

We assume for f :

$$\left. \begin{aligned} f &\in L^\infty(0, T; L^n(\Omega, \mathbb{R}^n)) \\ Df &\in L^\infty(0, T; L_{loc}^n(\Omega, \mathbb{R}^{n \times n})) \\ \Delta f &\in L^\infty(0, T; L_{loc}^n(\Omega, \mathbb{R}^n)) \end{aligned} \right\} \quad (7.1)$$

7.1 isotropic hardening

Theorem 7.1 *Let (7.1) and the safe load condition (3.1) hold true, then the strain tensor $\varepsilon(v_\mu)$ of penalized hardening is uniformly bounded in $L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n}))$.*

proof Let $\omega \in L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n}))$ with $\operatorname{div} \omega \in L^\infty(0, T; L^n(\Omega, \mathbb{R}^n))$ and $\|\omega\|_{L^2(L^2)} = 1$. Consider the test function

$$\begin{aligned} \tau &= \omega \\ \eta &= |\omega_D| - \kappa. \end{aligned} \quad (7.2)$$

test the weak formulation (5.8) with $(\sigma_\mu - \tau, \xi_\mu - \eta)$ where (σ_μ, ξ_μ) are solutions of the penalized equation.

We examine the tested penalty term $(G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta))$

$$\begin{aligned} &(G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta)) \\ &= \frac{1}{\mu} \int_{\Omega} (|\sigma_{\mu D}| - (\kappa + \xi_\mu))_+ \left(\frac{\sigma_{\mu D}}{|\sigma_{\mu D}|} : (\sigma_\mu - \omega) \right) dx - \frac{1}{\mu} \int_{\Omega} (|\sigma_{\mu D}| - (\kappa + \xi_\mu))_+ (\xi_\mu - |\omega_D| + \kappa) dx \\ &\stackrel{\text{Cauchy Schwarz}}{\geq} \frac{1}{\mu} \int_{\Omega} (|\sigma_{\mu D}| - (\kappa + \xi_\mu))_+ (|\sigma_{\mu D}| - |\omega_D|) dx - \frac{1}{\mu} \int_{\Omega} (|\sigma_{\mu D}| - (\kappa + \xi_\mu))_+ (\xi_\mu - |\omega_D| + \kappa) dx \\ &= \frac{1}{\mu} \int_{\Omega} (|\sigma_{\mu D}| - (\kappa + \xi_\mu))_+ (|\sigma_{\mu D}| - (\kappa + \xi_\mu)) \geq 0. \end{aligned} \quad (7.3)$$

The definiteness of the tested penalty term yields the inequality

$$(A\dot{\sigma}_\mu, \sigma_\mu - \omega) + (H\dot{\xi}_\mu, \xi_\mu - (|\omega_D| - \kappa)) \leq (\varepsilon(v_\mu), \sigma_\mu - \omega) \quad (7.4)$$

sorting terms

$$(\varepsilon(v_\mu), \omega) \leq -(A\dot{\sigma}_\mu, \sigma_\mu) + (A\dot{\sigma}_\mu, \omega) - (H\dot{\xi}_\mu, \xi_\mu) + (H\dot{\xi}_\mu, |\omega_D|) - (H\dot{\xi}_\mu, \kappa) + (\varepsilon(v_\mu), \sigma_\mu). \quad (7.5)$$

Using the balance of forces (2.4) $(\varepsilon(v_\mu), \sigma_\mu) = -(v_\mu, f) + \int_{\Gamma_N} p v_\mu d\Gamma$ and integrate (7.5) from 0 to t

$$\begin{aligned} \int_0^t (\varepsilon(v_\mu), \omega) ds &\leq -\frac{1}{2}(A\sigma_\mu, \sigma_\mu) - \frac{1}{2}(H\xi_\mu, \xi_\mu) + \int_0^t (A\dot{\sigma}_\mu, \omega) ds \\ &\quad + \int_0^t (H\dot{\xi}_\mu, |\omega_D|) ds - \int_0^t (H\dot{\xi}_\mu, \kappa) ds - \int_0^t (v_\mu, f) ds + \int_0^t \int_{\Gamma_N} p v_\mu d\Gamma ds. \end{aligned} \quad (7.6)$$

The Hölder and Young inequality gives with use of $|\omega_D| \leq |\omega|$ almost everywhere the estimate

$$\begin{aligned} \int_0^t (\varepsilon(v_\mu), \omega) ds &\leq \frac{1}{2}(A\sigma_\mu, \sigma_\mu) + \frac{1}{2}(H\xi_\mu, \xi_\mu) + \int_0^t \|A\dot{\sigma}_\mu\|^2 ds + 2 \int_0^t \|\omega\|^2 ds + 2 \int_0^t \|H\dot{\xi}_\mu\|^2 ds \\ &\quad + \int_0^t \|v_\mu\|_{L^{\frac{n}{n-1}}} \cdot \|f\|_{L^n} ds + \int_0^t \|v_\mu\|_{L^1(\Gamma_N)} \cdot \|p\|_{L^\infty(\Gamma_N)} ds + t \cdot \kappa^2 |\Omega| \leq Const. \end{aligned} \quad (7.7)$$

We have $\|\varepsilon(v_\mu)\|_{L^2(L^2)} \leq Const$. By Korn's inequality we obtain $\|v_\mu\|_{L^2(H^1)} \leq Const$. \square

Theorem 7.2 *With the assumptions of theorem 7.1, the strain tensor $\varepsilon(v)$ with v solution of isotropic hardening holds*

$$\begin{aligned} \varepsilon(v) &\in L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n})) \\ v &\in L^2(0, T; H_{\Gamma_D}^1(\Omega, \mathbb{R}^n)). \end{aligned} \quad (7.8)$$

proof The convergence of $((\sigma_\mu, \xi_\mu), v_\mu)$ to $((\sigma, \xi), v)$ yields the statement. \square

7.2 kinematic hardening

Theorem 7.3 *Under the assumptions of theorem 7.1, the strain tensor $\varepsilon(v_\mu)$ of penalized kinematic hardening holds*

$$\|\varepsilon(v_\mu)\|_{L^2(L^2)} \leq \text{Const}.$$

proof Let $\omega \in L^2(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}))$ with $\text{div } \omega \in L^\infty(0, T; L^n(\Omega, \mathbb{R}^n))$ and $\|\omega\|_{L^2(L^2)} = 1$. Consider the testfunction

$$\begin{aligned} \tau &= \omega \\ \eta &= \xi_\mu - \sigma_\mu + \omega. \end{aligned} \tag{7.9}$$

Test equation (5.8) with $(\sigma_\mu - \tau, \xi_\mu - \eta)$ where (σ_μ, ξ_μ) are solutions.

The tested penalty term $(G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta))$ takes the following form

$$\begin{aligned} & (G'_\mu((\sigma_\mu, \xi_\mu)), (\sigma_\mu - \tau, \xi_\mu - \eta)) \\ &= \frac{1}{\mu} \int_\Omega \frac{(|\sigma_{\mu D} - \xi_{\mu D}| - \kappa)_+}{|\sigma_{\mu D} - \xi_{\mu D}|} \left((\sigma_{\mu D} - \xi_{\mu D}) : (\sigma_\mu - \omega) + (\xi_{\mu D} - \sigma_{\mu D}) : (\sigma_\mu - \omega) \right) \\ &= 0. \end{aligned} \tag{7.10}$$

Thus we have the inequality

$$(A\dot{\sigma}_\mu, \sigma_\mu - \omega) + (H\dot{\xi}_\mu, \sigma_\mu - \omega) \leq (\varepsilon(v_\mu), \sigma_\mu - \omega) \tag{7.11}$$

sorting terms

$$(\varepsilon(v_\mu), \omega) \leq (A\dot{\sigma}_\mu, \sigma_\mu) + (A\dot{\sigma}_\mu, \omega) - (H\dot{\xi}_\mu, \sigma_\mu) + (H\dot{\xi}_\mu, \omega) + (\varepsilon(v_\mu), \sigma_\mu). \tag{7.12}$$

Integrate from 0 to t and using the Young- and Hölder inequality.

With $(\varepsilon(v_\mu), \sigma_\mu) = -(v_\mu, f) + \int_{\Gamma_N} p v_\mu d\Gamma$ we have

$$\begin{aligned} \int_0^t (\varepsilon(v_\mu), \omega) ds &\leq \frac{1}{2} (A\sigma_\mu, \sigma_\mu) + \int_0^t \|A\dot{\sigma}_\mu\|^2 ds + \int_0^t \|\omega\|^2 ds + 2 \int_0^t \|H\dot{\xi}_\mu\|^2 ds \\ &+ 2 \int_0^t \|\sigma_\mu\|^2 ds + \int_0^t \|f\|_{L^n} \cdot \|v_\mu\|_{L^{\frac{n}{n-1}}} ds + \int_0^t \|v_\mu\|_{L^1(\Gamma_N)} \cdot \|p\|_{L^\infty(\Gamma_N)} ds \leq \text{Const}. \end{aligned} \tag{7.13}$$

Thus $\varepsilon(v_\mu)$ is bounded in $L^2(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}))$ independent of the viscosity coefficient μ .

□

Theorem 7.4 *We have for the strain tensor $\varepsilon(v)$, with v solution of kinematic hardening $\varepsilon(v) \in L^2(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n}))$ and $v \in L^2(0, T; H_{\Gamma_D}^1(\Omega, \mathbb{R}^n))$.*

proof The convergence of $((\sigma_\mu, \xi_\mu), v_\mu)$ to $((\sigma, \xi), v)$ yields the statement by using theorem 7.3. \square

7.3 Local differentiability of the stress tensor and hardening parameter

With the uniform boundedness of the strain tensor $\varepsilon(v_\mu)$ we are now able to show the local differentiability of the stress tensor σ and hardening parameter ξ . Seregin [Ser94] obtained the local differentiability for the stresses and hardening parameters with a dual method, without using a penalty approximation of the variational inequality (1.2).

Remark: To prove the differentiability we need more regularity for the elasticity tensor A and hardening modulus H : For the sake of brevity we take $A \in \text{hom}(\mathbb{R}_{sym}^{n \times n}, \mathbb{R}_{sym}^{n \times n})$ constant¹. The same assumption holds for the hardening modulus H .

Theorem 7.5 *With the assumptions of theorem 7.1 and the remark above we have: In the case of isotropic-, kinematic hardening the stress tensor and hardening parameter holds $\sigma \in L^2(0, T; H_{loc}^1(\Omega, \mathbb{R}_{sym}^{n \times n}))$, $\xi \in L^2(0, T; H_{loc}^1(\Omega, \mathbb{R}^m))$ with $m = 1$ or $m = n \times n$.*

proof Let $\theta \in C_o^\infty(\Omega)$ be a cutoff function and $0 < h < \frac{1}{2} \text{dist}(\text{supp } \theta, \partial\Omega)$. Test the penalized equation (5.8) with $-D_j^{-h}(\theta^2 D_j^h(\sigma_\mu, \xi_\mu))$.

$$\left(\theta A D_j^h \dot{\sigma}_\mu, \theta D_j^h \sigma_\mu\right) + \left(H \theta D_j^h \dot{\xi}_\mu, \theta D_j^h \xi_\mu\right) + \left(\theta D_j^h G'_\mu((\sigma_\mu, \xi_\mu)), \theta D_j^h(\sigma_\mu, \xi_\mu)\right) = \left(D_j^h \varepsilon(v_\mu), \theta^2 D_j^h \sigma_\mu\right) \quad (7.14)$$

By monotonicity, the tested penalty term reads

$$\left(\theta D_j^h G'_\mu((\sigma_\mu, \xi_\mu)), \theta D_j^h(\sigma_\mu, \xi_\mu)\right) \geq 0.$$

¹For example one can take the inverse Lamé-Navier Operator $A\sigma = \frac{1}{2\mu_0}\sigma - \frac{\lambda_0}{3\lambda_0+2\mu_0} \text{tr}(\sigma) \cdot Id$, where $\lambda_0, \mu_0 > 0$ are the Lamé constants of the material.

write

$$\begin{aligned}(\theta AD_j^h \dot{\sigma}_\mu, \theta D_j^h \sigma_\mu) &= \frac{1}{2} \frac{d}{dt} (\theta AD_j^h \sigma_\mu, \theta D_j^h \sigma_\mu) \\(H \theta D_j^h \dot{\xi}_\mu, \theta D_j^h \xi_\mu) &= \frac{1}{2} \frac{d}{dt} (H \theta D_j^h \xi_\mu, \theta D_j^h \xi_\mu).\end{aligned}$$

Integrate equation (7.14) from 0 to t and using the ellipticity of A , H we obtain

$$\frac{\alpha_A}{2} \|\theta D_j^h \sigma_\mu\|^2 + \frac{\alpha_H}{2} \|\theta D_j^h \xi_\mu\|^2 \leq \int_0^t (D_j^h \varepsilon(v_\mu), \theta^2 D_j^h \sigma_\mu) ds. \quad (7.15)$$

Using the balance of forces (2.4) on the left hand side yields

$$\int_0^t (D_j^h \varepsilon(v_\mu), \theta^2 D_j^h \sigma_\mu) ds = - \int_0^t (D_j^h v_\mu, \text{grad } \theta^2 D_j^h \sigma_\mu) ds - \int_0^t (D_j^h v_\mu, \theta^2 D_j^h f) ds.$$

We know that $\varepsilon(v_\mu)$ and v are uniform bounded, thus we obtain for $-\int_0^t (D_j^h v_\mu, \text{grad } \theta^2 D_j^h \sigma_\mu) ds$ and h small enough

$$\begin{aligned}- \int_0^t (D_j^h v_\mu, \text{grad } \theta^2 D_j^h \sigma_\mu) ds &\leq \gamma C_\theta \int_0^t \|\theta D_j^h \sigma_\mu\|^2 ds + \frac{1}{4\gamma} \int_0^t \|v_\mu\|_{H^1}^2 ds \\ &\leq \gamma C_\theta \int_0^t \|\theta D_j^h \sigma_\mu\|^2 ds + \text{Const}.\end{aligned}$$

We use discrete partial integration for $-\int_0^t (D_j^h v_\mu, \theta^2 D_j^h f) ds$ and obtain

$$- \int_0^t (D_j^h v_\mu, \theta^2 D_j^h f) ds = \int_0^t (v_\mu, D_j^{-h} \theta^2 D_j^h f) ds + \int_0^t (v_\mu, E_j^{-h} \theta^2 \Delta^h f) ds \leq \text{Const}.$$

Where $\Delta^h f = D_j^{-h} (D_j^h f)$ denotes the finite difference approximation to the Laplace operator Δf .

We obtain the inequality

$$\frac{\alpha_A}{2} \|\theta D_j^h \sigma_\mu\|^2 + \frac{\alpha_H}{2} \|\theta D_j^h \xi_\mu\|^2 \leq \text{Const} + \frac{1}{4\gamma} \text{Const} + \gamma C_\theta \int_0^t \|\theta D_j^h \sigma_\mu\|^2 ds.$$

and Gronwall's lemma yields

$$\begin{aligned}\|\theta D_j^h \sigma_\mu\|^2 &\leq \text{Const} \\ \|\theta D_j^h \xi_\mu\|^2 &\leq \text{Const}\end{aligned}$$

independent of the viscosity coefficient μ . By passing to the limit one gets the local differentiability for the stress tensor and hardening parameters of the initial hardening problem (1.2). \square

8 $L^\infty(L^2)$ -estimates for $\varepsilon(\dot{u}_\mu)$ and $(\dot{\sigma}_\mu, \dot{\xi}_\mu)$

In this section we derive $L^\infty(L^2)$ estimates for the velocities of the stress tensor and hardening parameters. We also show the existence of the initial value $(\dot{\sigma}_\mu, \dot{\xi}_\mu)(0)$.

We do this by giving an estimate of the form

$$\int_{\Omega} A\dot{\sigma}_\mu : \dot{\sigma}_\mu + H\dot{\xi}_\mu : \dot{\xi}_\mu dx|_T \leq \frac{1}{h} \int_0^h \int_{\Omega} A\dot{\sigma}_\mu : \dot{\sigma}_\mu + H\dot{\xi}_\mu : \dot{\xi}_\mu dx dt + K.$$

For the preceding calculations we need to extend the safe load condition (3.1).

extended safe load:

There exists a $(\tau, \eta) \in W^{2,\infty}(0, T; L^\infty(\Omega, \mathbb{R}_{\text{sym}}^{n \times n})) \times W^{1,\infty}(0, T; L^\infty(\Omega, \mathbb{R}^m))$ and $\delta > 0$ such that

$$\left. \begin{aligned} -\operatorname{div} \tau &= f \text{ in } \Omega \times [0, T] \\ \tau \cdot \vec{n} &= p \text{ on } \Gamma_N \times [0, T] \\ (\tau, \eta)(0) &= 0 \text{ in } \Omega \times \mathbb{R}^m \times \{t = 0\} \\ F(\tau, \eta) &\leq -\delta < 0. \end{aligned} \right\} \quad (8.1)$$

The novell feature in this hypothesis is $\dot{\tau} \in L^\infty(0, T; L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}))$.

Theorem 8.1 *Let the assumptions of section 1 and the extended safe load condition (8.1) hold true, let $h \in (0, T)$, then there holds the estimate*

$$\int_0^h \int_{\Omega} |\varepsilon(\dot{u}_\mu)|^2 dx dt \leq K \int_0^h \int_{\Omega} |\dot{\sigma}_\mu|^2 + |\dot{\xi}_\mu|^2 dx dt. \quad (8.2)$$

proof We test the pointwise hardening law (5.7) with $(\varepsilon(\dot{u}_\mu), |\varepsilon(\dot{u}_\mu)|)^\top$. In both cases, isotropic and kinematic, the tested penalty terms cancel out after the use of the Cauchy Schwarz inequality. Application of Young's inequality gives the desired result. \square

Theorem 8.2 *We have*

$$\frac{1}{h} \int_0^h \int_{\Omega} \varepsilon(\dot{u}_\mu) : \dot{\sigma}_\mu dx dt \leq \frac{K}{h} \int_0^h \int_{\Omega} |\dot{\sigma}_\mu|^2 + |\dot{\xi}_\mu|^2 dx dt + K. \quad (8.3)$$

proof Let (τ, η) satisfy the safe load condition (8.1). Then

$$\begin{aligned} \frac{1}{h} \int_0^h \int_{\Omega} \varepsilon(\dot{u}_\mu) : \dot{\sigma}_\mu &= \frac{1}{h} \int_0^h \int_{\Omega} \underbrace{\varepsilon(\dot{u}_\mu) : (\dot{\sigma}_\mu - \dot{\tau})}_{=0} dx dt + \frac{1}{h} \int_0^h \int_{\Omega} \varepsilon(\dot{u}_\mu) : \dot{\tau} dx dt \\ &\stackrel{\text{Young}}{\leq} K_{\dot{\tau}} + \frac{\delta}{h} \int_0^h \int_{\Omega} |\varepsilon(\dot{u}_\mu)|^2 dx dt \\ &\stackrel{(8.2)}{\leq} K_{\dot{\tau}} + \frac{K}{h} \int_0^h \int_{\Omega} |\dot{\sigma}_\mu|^2 + |\dot{\xi}_\mu|^2 dx dt. \end{aligned} \quad (8.4)$$

□

Theorem 8.3 *Under the assumptions of section 1 and the extended safe load condition (8.1) there holds the estimate*

$$\int_{\Omega} A\dot{\sigma}_{\mu} : \dot{\sigma}_{\mu} + H\dot{\xi}_{\mu} : \dot{\xi}_{\mu} dx \Big|_T \leq \frac{1}{h} \int_0^h \int_{\Omega} A\dot{\sigma}_{\mu} : \dot{\sigma}_{\mu} + H\dot{\xi}_{\mu} : \dot{\xi}_{\mu} dx dt + K. \quad (8.5)$$

proof Let $0 < \rho < T$ and $t_0 \in (0, \rho)$ and apply the finite difference Operator D_t^{-k} , $0 < k \ll t_0$, in time to the pointwise a.e. equation (5.7) and then test with $D_t^{-k}(\sigma_{\mu}, \xi_{\mu})$

$$\int_{\Omega} D_t^{-k} \varepsilon(\dot{u}_{\mu}) : D_t^{-k} \sigma_{\mu} dx = \int_{\Omega} A D_t^{-k} \dot{\sigma}_{\mu} : D_t^{-k} \sigma_{\mu} + H D_t^{-k} \dot{\xi}_{\mu} : D_t^{-k} \xi_{\mu} dx + \int_{\Omega} D_t^{-k} G'_{\mu}(\sigma_{\mu}, \xi_{\mu}) : D_t^{-k}(\sigma_{\mu}, \xi_{\mu}) dx. \quad (8.6)$$

A zero addition with $D_t^{-k} \tau$, where τ satisfies the extended safe load condition (8.1), in the $\varepsilon(u_{\mu})$ -term leads to

$$\int_{\Omega} D_t^{-k} \varepsilon(\dot{u}_{\mu}) : D_t^{-k} \tau dx = \int_{\Omega} A D_t^{-k} \dot{\sigma}_{\mu} : D_t^{-k} \sigma_{\mu} + H D_t^{-k} \dot{\xi}_{\mu} : D_t^{-k} \xi_{\mu} dx + \underbrace{\int_{\Omega} D_t^{-k} G'_{\mu}(\sigma_{\mu}, \xi_{\mu}) : D_t^{-k}(\sigma_{\mu}, \xi_{\mu}) dx}_{\geq 0}. \quad (8.7)$$

By virtue of the monotonicity of G'_{μ} , the tested penalty term is non negative. We now integrate (8.7) from t_0 to $T - \rho$ and use discrete partial integration on the left handside

$$\begin{aligned} & - \int_{t_0+k}^{T-\rho} \int_{\Omega} \varepsilon(\dot{u}_{\mu}) : D_t^{+k} D_t^{-k} \tau dx dt + \frac{1}{k} \int_{t_0}^{t_0+k} \int_{\Omega} \varepsilon(\dot{u}_{\mu})(t) : D_t^{-k} \tau dx dt - \frac{1}{k} \int_{T-\rho}^{T-\rho+k} \int_{\Omega} \varepsilon(\dot{u}_{\mu}) : D_t^{-k} \tau dx dt \\ & \geq \frac{1}{2} \int_{\Omega} A D_t^{-k} \sigma_{\mu} : D_t^{-k} \sigma_{\mu} + H D_t^{-k} \xi_{\mu} : D_t^{-k} \xi_{\mu} dx \Big|_{t_0}^T. \end{aligned} \quad (8.8)$$

We now let $\rho \rightarrow 0$, by a theorem about Lebesgue points we procure from (8.8) for almost all $t_0 \in (0, T)$

$$- \int_{t_0}^T \int_{\Omega} \varepsilon(\dot{u}_{\mu}) : \ddot{\tau} dx dt + \int_{\Omega} \varepsilon(\dot{u}_{\mu}) : \dot{\tau} dx \Big|_{t_0} - \int_{\Omega} \varepsilon(\dot{u}_{\mu}) : \dot{\tau} dx \Big|_T \geq \frac{1}{2} \int_{\Omega} A \dot{\sigma}_{\mu} : \dot{\sigma}_{\mu} + H \dot{\xi}_{\mu} : \dot{\xi}_{\mu} dx \Big|_{t_0}^T. \quad (8.9)$$

Integrating this inequality over t_0 from 0 to h and multiplying with $\frac{1}{h}$ yields

$$\begin{aligned} \frac{1}{2} \int_{\Omega} A\dot{\sigma}_{\mu} : \dot{\sigma}_{\mu} + H\dot{\xi}_{\mu} : \dot{\xi}_{\mu} dx \Big|_T \leq & \frac{1}{2} \frac{1}{h} \int_0^h \int_{\Omega} A\dot{\sigma}_{\mu} : \dot{\sigma}_{\mu} + H\dot{\xi}_{\mu} : \dot{\xi}_{\mu} dx dt + \underbrace{\frac{1}{h} \int_0^h \int_{\Omega} \varepsilon(\dot{u}_{\mu}) : \dot{\tau} dx dt}_{(*)} \\ & + \underbrace{\int_{\Omega} \varepsilon(\dot{u}_{\mu}) : \dot{\tau} dx \Big|_T}_{(**)} + \hat{K}. \end{aligned} \quad (8.10)$$

The constant \hat{K} comes from the term $\int_{t_0}^T \int_{\Omega} \varepsilon(\dot{u}_{\mu}) : \dot{\tau} dx dt$:

We used Young's inequality then the extended safe load condition (8.1) and the uniform $L^2(L^2)$ -estimates from section 7. The terms $(*)$, $(**)$ can be absorbed, to do this we first use Young's inequality and then theorem 8.2. Thus

$$\int_{\Omega} A\dot{\sigma}_{\mu} : \dot{\sigma}_{\mu} + H\dot{\xi}_{\mu} : \dot{\xi}_{\mu} dx \Big|_T \leq \frac{1}{h} \int_0^h \int_{\Omega} A\dot{\sigma}_{\mu} : \dot{\sigma}_{\mu} + H\dot{\xi}_{\mu} : \dot{\xi}_{\mu} dx dt + K. \quad (8.11)$$

And this is the statement of the theorem. \square

Theorem 8.4 *We have $(\dot{\sigma}_{\mu}, \dot{\xi}_{\mu}) \in L^{\infty}(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n})) \times L^{\infty}(0, T; L^2(\Omega, \mathbb{R}^m))$, where $m = 1$ or $m = n \times n$. Furthermore $(\dot{\sigma}_{\mu}, \dot{\xi}_{\mu})(0)$ exists.*

proof This follows by the preceding theorems of this section. \square

This theorem and the convergence of $(\dot{\sigma}_{\mu}, \dot{\xi}_{\mu}) \rightarrow (\sigma, \xi)$ finally gives:

Theorem 8.5 *The time derivatives $(\dot{\sigma}_{\mu}, \dot{\xi}_{\mu})$ of the stress tensor and hardening parameter, solution of (1.2) belong to the space $L^{\infty}(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n})) \times L^{\infty}(0, T; L^2(\Omega, \mathbb{R}^m))$, where $m = 1$ or $m = n \times n$ and $(\dot{\sigma}, \dot{\xi})(0)$ exists.*

As a consequence we note

Theorem 8.6 *The strain tensor $\varepsilon(\dot{u}_{\mu})$ of the displacement velocities is contained in the space $L^{\infty}(0, T; L^2(\Omega, \mathbb{R}_{sym}^{n \times n}))$, with the uniform estimate*

$$\|\varepsilon(\dot{u}_{\mu})\|_{L^{\infty}(L^2)} \leq Const$$

as $\mu \rightarrow 0$.

9 A static hardening model

In the previous sections we considered a quasi-static hardening problem, whose formulation is due to Johnson [Joh78]. Following Temam [Tem85] we introduce a static hardening model based on the Hencky model of perfect elasto-plasticity.

We define the following sets:

$$\mathcal{K} = \{(\sigma, \xi) \mid F(\sigma, \xi) \leq 0\}$$

$$\mathcal{M} = \{(\sigma, \xi) \in L^2(\Omega, \mathbb{R}_{\text{sym}}^{n \times n}) \times L^2(\Omega, \mathbb{R}^m) \mid \sigma \cdot \vec{n} = p, \operatorname{div} \sigma \in L^n(\Omega, \mathbb{R}^n)\}.$$

Then the static hardening Problem is to find a minimum of

$$J(\sigma, \xi) = \frac{1}{2}(A\sigma, \sigma) + \frac{1}{2}(H\xi, \xi) \quad (9.1)$$

over the set $\mathcal{K} \cap \mathcal{M} \cap \{\sigma \mid -\operatorname{div} \sigma = f \text{ in } \Omega\}$. Where

$$\begin{aligned} f &\in L^n(\Omega, \mathbb{R}^n) \\ p &\in L^\infty(\partial\Omega, \mathbb{R}^n). \end{aligned}$$

The weak formulation is, to find $((\sigma, \xi), u) \in (\mathcal{M} \cap \mathcal{K}) \times BD(\Omega)$ such that

$$(A\sigma, \tau - \sigma) + (H\xi, \eta - \xi) + \langle u, \operatorname{div}(\tau - \sigma) \rangle \geq 0 \quad (9.2)$$

$$\begin{aligned} (\sigma, \nabla w) &= \langle f, w \rangle + \int_{\Gamma_N} p w \, do \quad \forall w \in H_{\Gamma_D}^1(\Omega, \mathbb{R}^n) \\ u &= 0 \text{ on } \Gamma_D. \end{aligned} \quad (9.3)$$

We will use the same type of approximation as in section 2, and we obtain similar results.

The penalized problem is to find $((\sigma_\mu, \xi_\mu), u_\mu) \in \mathcal{M} \times BD(\Omega)$ such that

$$(A\sigma, \tau - \sigma) + (H\xi, \eta - \xi) + \langle u, \operatorname{div}(\tau - \sigma) \rangle + (G'_\mu((\sigma_\mu, \xi_\mu)), (\tau - \sigma_\mu, \eta - \xi)) = 0 \quad (9.4)$$

$$\begin{aligned} (\sigma_\mu, \nabla w) &= \langle f, w \rangle + \int_{\Gamma_N} p w \, do \quad \forall w \in H_{\Gamma_D}^1(\Omega, \mathbb{R}^n) \\ u_\mu &= 0 \text{ on } \Gamma_D. \end{aligned} \quad (9.5)$$

Under the assumption of a safe load condition we are able to show the existence of the solutions to the static and penalized static hardening problem. We have the estimates for the solutions of the penalized problem independent of μ

$$\begin{aligned}\|\sigma_\mu\|_{L^2} &\leq Const \\ \|\xi_\mu\|_{L^2} &\leq Const.\end{aligned}$$

Like in the case of quasi-static hardening, for fixed viscosity coefficient μ the displacement is contained in $H^1(\Omega, \mathbb{R}^n)$

$$\begin{aligned}\|u_\mu\|_{H^1} &\leq \frac{1}{\mu} Const \\ \|\varepsilon(u_\mu)\|_{L^2} &\leq \frac{1}{\mu} Const.\end{aligned}$$

And the pointwise almost everywhere equation

$$\begin{pmatrix} A\sigma_\mu \\ H\xi_\mu \end{pmatrix} + \begin{pmatrix} \frac{\partial}{\partial\sigma_\mu} G_\mu(\sigma_\mu, \xi_\mu) \\ \frac{\partial}{\partial\xi_\mu} G_\mu(\sigma_\mu, \xi_\mu) \end{pmatrix} = \begin{pmatrix} \varepsilon(u_\mu) \\ 0 \end{pmatrix} \quad (9.6)$$

holds in Ω . The convergence of the solutions of the penalized model can be shown in the same way as in section 6.

If we use the same (but not time dependent) testfunctions as in section 7, we obtain the uniform estimate $\|u_\mu\|_{H^1} \leq Const$ and thus $u \in H^1$.

By using finite differences, we are able to show that $\sigma, \xi \in H_{loc}^1$.

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